深圳市翔芯微科技有限公司
Shenzhen Gity Cheunk oore Mioro Tedhmolovy Go．．Ltd．

# 3．3V－Powered，10Mbps and Slew－Rate－Limited True RS－485／RS－422 Transceivers 

## General Description

The MAX3483，MAX3485，MAX3486，MAX3488， MAX3490，and MAX3491 are 3．3V，low－power trans－ ceivers for RS－485 and RS－422 communication．Each part contains one driver and one receiver．The MAX3483 and MAX3488 feature slew－rate－limited dri－ vers that minimize EMI and reduce reflections caused by improperly terminated cables，allowing error－free data transmission at data rates up to 250 kbps ．The par－ tially slew－rate－limited MAX3486 transmits up to 2．5Mbps．The MAX3485，MAX3490，and MAX3491 transmit at up to 10 Mbps ．
Drivers are short－circuit current limited and are protect－ ed against excessive power dissipation by thermal shutdown circuitry that places the driver outputs into a high－impedance state．The receiver input has a fail－safe feature that guarantees a logic－high output if both inputs are open circuit．
The MAX3488，MAX3490，and MAX3491 feature full－ duplex communication，while the MAX3483，MAX3485， and MAX3486 are designed for half－duplex communi－ cation．

Applications
Low－Power RS－485／RS－422 Transceivers
Telecommunications
Transceivers for EMI－Sensitive Applications Industrial－Control Local Area Networks
Features
－Operate from a Single 3．3V Supply－ No Charge Pump！
－Interoperable with＋5V Logic
－8ns Max Skew（MAX3485／MAX3490／MAX3491）
－Slew－Rate Limited for Errorless Data Transmission （MAX3483／MAX3488）
－2nA Low－Current Shutdown Mode （MAX3483／MAX3485／MAX3486／MAX3491）
－-7 V to +12 V Common－Mode Input Voltage Range
－Allows up to 32 Transceivers on the Bus
－Full－Duplex and Half－Duplex Versions Available
－Industry Standard 75176 Pinout
（MAX3483／MAX3485／MAX3486）
－Current－Limiting and Thermal Shutdown for Driver Overload Protection

Ordering Information

| PART | TEMP．RANGE | PIN－PACKAGE |
| :--- | ---: | :--- |
| MAX3483CPA | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | 8 Plastic DIP |
| MAX3483CSA | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | 8 SO |
| MAX3483C／D | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | Dice ${ }^{*}$ |
| MAX3483EPA | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 8 Plastic DIP |
| MAX3483ESA | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 8 SO |
| MAX3485CPA | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | 8 Plastic DIP |
| MAX3485CSA | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | 8 SO |
| MAX3485C／D | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | Dice ${ }^{*}$ |
| MAX3485EPA | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 8 Plastic DIP |
| MAX3485ESA | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 8 SO |

Ordering Information continued at end of data sheet．
＊Contact factory for for dice specifications．
Selection Table

| PART NUMBER | GUARANTEED DATA RATE （Mbps） | SUPPLY VOLTAGE <br> （V） | HALF／FULL DUPLEX | SLEW－RATE <br> LIMITED | DRIVER／ RECEIVER ENABLE | SHUTDOWN CURRENT （nA） | $\begin{gathered} \text { PIN } \\ \text { COUNT } \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| MAX3483 | 0.25 | 3.0 to 3.6 | Half | Yes | Yes | 2 | 8 |
| MAX3485 | 10 |  | Half | No | Yes | 2 | 8 |
| MAX3486 | 2.5 |  | Half | Yes | Yes | 2 | 8 |
| MAX3488 | 0.25 |  | Full | Yes | No | － | 8 |
| MAX3490 | 10 |  | Full | No | No | － | 8 |
| MAX3491 | 10 |  | Full | No | Yes | 2 | 14 |

Call toll free 1－800－998－8800 for free samples or literature．

### 3.3V-Powered, 10Mbps and Slew-Rate-Limited True RS-485/RS-422 Transceivers

## ABSOLUTE MAXIMUM RATINGS




14-Pin Plastic DIP (derate $10 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ ) ...... 800 mW 14 -Pin SO (derate $8.33 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ )................ 667 mW Operating Temperature Ranges
MAX34__C
$0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$

Torag Tomperature Rang
Lead Temperature (soldering, 10 sec ) ............................. $+300^{\circ} \mathrm{C}$

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## DC ELECTRICAL CHARACTERISTICS

( $\mathrm{V} C \mathrm{C}=3.3 \mathrm{~V} \pm 0.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\mathrm{MAX}}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$ )

| PARAMETER | SYMBOL | CONDITIONS |  | MIN | TYP MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Differential Driver Output | VOD | $R_{L}=100 \Omega$ (RS-422), Figure 4 |  | 2.0 |  | V |
|  |  | $\mathrm{R}_{\mathrm{L}}=54 \Omega$ (RS-485), Figure 4 |  | 1.5 |  |  |
|  |  | $\mathrm{R}_{\mathrm{L}}=60 \Omega$ (RS-485), $\mathrm{V}_{\mathrm{CC}}=3.3 \mathrm{~V}$, Figure 5 |  | 1.5 |  |  |
| Change in Magnitude of Driver Differential Output Voltage for Complementary Output States (Note 1) | $\Delta \mathrm{V}_{\mathrm{OD}}$ | $\mathrm{R}_{\mathrm{L}}=54 \Omega$ or $100 \Omega$, Figure 4 |  |  | 0.2 | V |
| Driver Common-Mode Output Voltage | Voc | $\mathrm{R}_{\mathrm{L}}=54 \Omega$ or $100 \Omega$, Figure 4 |  |  | 3 | V |
| Change in Magnitude of Common-Mode Output Voltage (Note 1) | $\Delta \mathrm{V}_{\text {OC }}$ | $\mathrm{R}_{\mathrm{L}}=54 \Omega$ or $100 \Omega$, Figure 4 |  |  | 0.2 | V |
| Input High Voltage | $\mathrm{V}_{\mathrm{IH}}$ | DE, DI, RE |  | 2.0 |  | V |
| Input Low Voltage | VIL | DE, DI, $\overline{R E}$ |  |  | 0.8 | V |
| Logic Input Current | IIN1 | DE, DI, $\overline{\mathrm{RE}}$ |  |  | $\pm 2$ | $\mu \mathrm{A}$ |
| Input Current (A, B) | IIN2 | $\begin{aligned} & \mathrm{DE}=0 \mathrm{~V}, \\ & \mathrm{~V} C \mathrm{C}=0 \mathrm{~V} \text { or } 3.6 \mathrm{~V} \end{aligned}$ | V IN $=12 \mathrm{~V}$ |  | 1.0 | mA |
|  |  |  | $\mathrm{V}_{\mathrm{IN}}=-7 \mathrm{~V}$ |  | -0.8 |  |
| Output Leakage (Y, Z) | lo | $\begin{aligned} & \mathrm{DE}=0 \mathrm{~V}, \overline{\mathrm{RE}}=0 \mathrm{~V}, \\ & \mathrm{~V} \mathrm{CC}=0 \mathrm{~V} \text { or } 3.6 \mathrm{~V}, \mathrm{MAX} 3491 \end{aligned}$ | Vout $=12 \mathrm{~V}$ |  | 20 | $\mu \mathrm{A}$ |
|  |  |  | VOUT $=-7 \mathrm{~V}$ |  | -20 |  |
| Output Leakage (Y, Z) in Shutdown Mode | lo | $\begin{aligned} & \mathrm{DE}=0 \mathrm{~V}, \overline{\mathrm{RE}}=\mathrm{V}_{\mathrm{CC}}, \\ & \mathrm{~V}_{\mathrm{CC}}=0 \mathrm{~V} \text { or } 3.6 \mathrm{~V}, \mathrm{MAX} 4491 \end{aligned}$ | Vout $=12 \mathrm{~V}$ |  | 1 | $\mu \mathrm{A}$ |
|  |  |  | VOUT $=-7 \mathrm{~V}$ |  | -1 |  |
| Receiver Differential Threshold Voltage | $\mathrm{V}_{\text {TH }}$ | $-7 \mathrm{~V} \leq \mathrm{V}_{\mathrm{CM}} \leq 12 \mathrm{~V}$ |  | -0.2 | 0.2 | V |
| Receiver Input Hysteresis | $\Delta \mathrm{V}_{\text {TH }}$ | $\mathrm{V}_{\mathrm{CM}}=0 \mathrm{~V}$ |  | 50 |  | mV |
| Receiver Output High Voltage | V OH | IOUT $=-1.5 \mathrm{~mA}, \mathrm{~V}$ ID $=200 \mathrm{mV}$, Figure 6 |  | $\mathrm{V}_{\text {CC }}-0.4$ |  | V |
| Receiver Output Low Voltage | VOL | IOUT $=2.5 \mathrm{~mA}, \mathrm{~V}$ ID $=200 \mathrm{mV}$, Figure 6 |  |  | 0.4 | V |
| Three-State (High Impedance) Output Current at Receiver | lozr | $\mathrm{V}_{\text {CC }}=3.6 \mathrm{~V}, 0 \mathrm{~V} \leq \mathrm{V}_{\text {OUT }} \leq \mathrm{V}_{\text {CC }}$ |  |  | $\pm 1$ | $\mu \mathrm{A}$ |
| Receiver Input Resistance | RIN | $-7 \mathrm{~V} \leq \mathrm{V}_{\mathrm{CM}} \leq 12 \mathrm{~V}$ |  | 12 |  | k $\Omega$ |

### 3.3V-Powered, 10Mbps and Slew-Rate-Limited True RS-485/RS-422 Transceivers

## DC ELECTRICAL CHARACTERISTICS (continued)

$\left(\mathrm{V}_{\mathrm{CC}}=3.3 \mathrm{~V} \pm 0.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{MIN}}\right.$ to $\mathrm{T}_{\mathrm{MAX}}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$ )

| PARAMETER | SYMBOL | CONDITIONS |  | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Supply Current | Icc | No load,$\mathrm{DI}=0 \mathrm{~V} \text { or } \mathrm{V}_{\mathrm{CC}}$ | $\begin{aligned} & \mathrm{DE}=\mathrm{V}_{\mathrm{CC}}, \\ & \mathrm{RE}=0 \mathrm{~V} \text { or } \mathrm{V}_{\mathrm{CC}} \end{aligned}$ |  | 1.1 | 2.2 | mA |
|  |  |  | $\begin{aligned} & \mathrm{DE}=0 \mathrm{~V}, \\ & \mathrm{RE}=0 \mathrm{~V} \end{aligned}$ |  | 0.95 | 1.9 |  |
| Supply Current in Shutdown Mode | ISHDN | $\mathrm{DE}=0 \mathrm{~V}, \overline{\mathrm{RE}}=\mathrm{V}_{\mathrm{CC}}, \mathrm{DI}=\mathrm{V}_{\mathrm{CC}}$ or 0 V |  |  | 0.002 | 1 | $\mu \mathrm{A}$ |
| Driver Short-Circuit Output Current | IOSD | $\mathrm{V}_{\text {OUT }}=-7 \mathrm{~V}$ |  |  |  | -250 | mA |
|  |  | VOUT $=12 \mathrm{~V}$ |  |  |  | 250 |  |
| Receiver Short-Circuit Output Current | IOSR | $\mathrm{V} \leq \mathrm{V}_{\mathrm{RO}} \leq \mathrm{V}_{\mathrm{CC}}$ |  | $\pm 8$ |  | $\pm 60$ | mA |

DRIVER SWITCHING CHARACTERISTICS—MAX3485, MAX3490, and MAX3491
$\left(\mathrm{V}_{\mathrm{CC}}=3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}\right)$

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Driver Differential Output Delay | tDD | $\mathrm{R}_{\mathrm{L}}=60 \Omega$, Figure 7 | 1 | 22 | 35 | ns |
| Driver Differential Output Transition Time | tTD | $\mathrm{R}_{\mathrm{L}}=60 \Omega$, Figure 7 | 3 | 8 | 25 | ns |
| Driver Propagation Delay, Low-to-High Level | tpli | $\mathrm{R}_{\mathrm{L}}=27 \Omega$, Figure 8 | 7 | 22 | 35 | ns |
| Driver Propagation Delay, High-to-Low Level | tPHL | $\mathrm{R}_{\mathrm{L}}=27 \Omega$, Figure 8 | 7 | 22 | 35 | ns |
| \|tPLH - tphL | Driver Propagation Delay Skew (Note 2) | tpDS | $\mathrm{R}_{\mathrm{L}}=27 \Omega$, Figure 8 |  |  | 8 | ns |
| DRIVER OUTPUT ENABLE/DISABLE TIMES (MAX3485/MAX3491 only) |  |  |  |  |  |  |
| Driver Output Enable Time to Low Level | tPZL | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 10 |  | 45 | 90 | ns |
| Driver Output Enable Time to High Level | tpZH | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 9 |  | 45 | 90 | ns |
| Driver Output Disable Time from High Level | tPHZ | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 9 |  | 40 | 80 | ns |
| Driver Output Disable Time from Low Level | tpLZ | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 10 |  | 40 | 80 | ns |
| Driver Output Enable Time from Shutdown to Low Level | tpSL | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 10 |  | 650 | 900 | ns |
| Driver Output Enable Time from Shutdown to High Level | tPSH | RL $=110 \Omega$, Figure 9 |  | 650 | 900 | ns |

## DRIVER SWITCHING CHARACTERISTICS—MAX3486

$\left(\mathrm{V} C \mathrm{C}=3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}\right)$

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Driver Differential Output Delay | tDD | $\mathrm{R}_{\mathrm{L}}=60 \Omega$, Figure 7 | 24 | 48 | 70 | ns |
| Driver Differential Output Transition Time | tTD | $\mathrm{R}_{\mathrm{L}}=60 \Omega$, Figure 7 | 15 | 35 | 60 | ns |
| Driver Propagation Delay, Low-to-High Level | tPLH | $R_{L}=27 \Omega$, Figure 8 | 20 | 48 | 70 | ns |
| Driver Propagation Delay, High-to-Low Level | tPHL | $\mathrm{R}_{\mathrm{L}}=27 \Omega$, Figure 8 | 20 | 48 | 70 | ns |
| \|tPLH - tPhL| Driver Propagation Delay Skew (Note 2) | tpDS | $\mathrm{R}_{\mathrm{L}}=27 \Omega$, Figure 8 |  |  | 11 | ns |
| Driver Output Enable Time to Low Level | tPZL | $R_{L}=110 \Omega$, Figure 10 |  | 55 | 100 | ns |
| Driver Output Enable Time to High Level | tPZH | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 9 |  | 55 | 100 | ns |
| Driver Output Disable Time from High Level | tPHZ | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 9 |  | 45 | 80 | ns |
| Driver Output Disable Time from Low Level | tPLZ | $R_{L}=110 \Omega$, Figure 10 |  | 45 | 80 | ns |
| Driver Output Enable Time from Shutdown to Low Level | tpSL | $R_{L}=110 \Omega$, Figure 10 |  | 700 | 1000 | ns |
| Driver Output Enable Time from Shutdown to High Level | tPSH | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 9 |  | 700 | 1000 | ns |

# 3.3V-Powered, 10Mbps and Slew-Rate-Limited True RS-485/RS-422 Transc eivers 

DRIVER SWITCHING CHARACTERISTICS—MAX3483 and MAX3488
$\left(\mathrm{V}_{\mathrm{CC}}=3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}\right)$

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Driver Differential Output Delay | tDD | $\mathrm{R}_{\mathrm{L}}=60 \Omega$, Figure 7 | 600 | 900 | 1400 | ns |
| Driver Differential Output Transition Time | tTD | $\mathrm{R}_{\mathrm{L}}=60 \Omega$, Figure 7 | 400 | 700 | 1200 | ns |
| Driver Propagation Delay, Low-to-High Level | tplh | $\mathrm{R}_{\mathrm{L}}=27 \Omega$, Figure 8 | 700 | 1000 | 1500 | ns |
| Driver Propagation Delay, High-to-Low Level | tpHL | $\mathrm{R}_{\mathrm{L}}=27 \Omega$, Figure 8 | 700 | 1000 | 1500 | ns |
| \|tPLH - tPHL| Driver Propagation Delay Skew (Note 2) | tpDS | $\mathrm{R}_{\mathrm{L}}=27 \Omega$, Figure 8 |  | 100 |  | ns |
| DRIVER OUTPUT ENABLE/DISABLE TIMES (MAX3483 only) |  |  |  |  |  |  |
| Driver Output Enable Time to Low Level | tPZL | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 10 |  | 900 | 1300 | ns |
| Driver Output Enable Time to High Level | tpZH | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 9 |  | 600 | 800 | ns |
| Driver Output Disable Time from High Level | tPHZ | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 9 |  | 50 | 80 | ns |
| Driver Output Disable Time from Low Level | tpLZ | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 10 |  | 50 | 80 | ns |
| Driver Output Enable Time from Shutdown to Low Level | tpSL | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 10 |  | 1.9 | 2.7 | $\mu \mathrm{s}$ |
| Driver Output Enable Time from Shutdown to High Level | tPSH | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 9 |  | 2.2 | 3.0 | $\mu \mathrm{s}$ |

## RECEIVER SWITCHING CHARACTERISTICS

$\left(\mathrm{V}_{\mathrm{CC}}=3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}\right)$

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Time to Shutdown | tshdn | MAX3483/MAX3485/MAX3486/MAX3491 only (Note 3) | 80 | 190 | 300 | ns |
| Receiver Propagation Delay, Low-to-High Level | trpLH | V ID $=0 \mathrm{~V}$ to $3.0 \mathrm{~V}, \mathrm{CLL}^{\text {= }} 15 \mathrm{pF}$, Figure 11 | 25 | 65 | 90 | ns |
|  |  | MAX3483/MAX3488 | 25 | 75 | 120 |  |
| Receiver Propagation Delay, High-to-Low Level | trPHL | V ID $=0 \mathrm{~V}$ to $3.0 \mathrm{~V}, \mathrm{CL}=15 \mathrm{pF}$, Figure 11 | 25 | 65 | 90 | ns |
|  |  | MAX3483/MAX3488 | 25 | 75 | 120 |  |
| \|tPLH - tphl| Receiver Propagation Delay Skew | trPDS | V ID $=0 \mathrm{~V}$ to $3.0 \mathrm{~V}, \mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}$, Figure 11 |  |  | 10 | ns |
|  |  | MAX3483/MAX3488 |  |  | 20 |  |
| Receiver Output Enable Time to Low Level | tPRZL | $C_{L}=15 p F$, Figure 12, MAX3483/MAX3485/MAX3486/MAX3491 only |  | 25 | 50 | ns |
| Receiver Output Enable Time to High Level | tpRZH | $C_{L}=15 p F$, Figure 12, MAX3483/MAX3485/MAX3486/MAX3491 only |  | 25 | 50 | ns |
| Receiver Output Disable Time from High Level | tPRHZ | $C_{L}=15 p F$, Figure 12, MAX3483/MAX3485/MAX3486/MAX3491 only |  | 25 | 45 | ns |
| Receiver Output Disable Time from Low Level | tPRLZ | $C_{L}=15 p F$, Figure 12, MAX3483/MAX3485/MAX3486/MAX3491 only |  | 25 | 45 | ns |
| Receiver Output Enable Time from Shutdown to Low Level | tpRSL | $C_{L}=15 p F$, Figure 12, MAX3483/MAX3485/MAX3486/MAX3491 only |  | 720 | 1400 | ns |
| Receiver Output Enable Time from Shutdown to High Level | tPRSH | $C_{L}=15 p F$, Figure 12, MAX3483/MAX3485/MAX3486/MAX3491 only |  | 720 | 1400 | ns |

Note 1: $\Delta \mathrm{V}_{\mathrm{OD}}$ and $\Delta \mathrm{V}_{\mathrm{OC}}$ are the changes in $\mathrm{V}_{\mathrm{OD}}$ and $\mathrm{V}_{\mathrm{OC}}$, respectively, when the D input changes state.
Note 2: Measured on |tpLH (Y) - tphl (Y)| and |tpLH (Z) - tphl (Z)|.
Note 3: The transceivers are put into shutdown by bringing RE high and DE low. If the inputs are in this state for less than 80ns, the parts are guaranteed not to enter shutdown. If the inputs are in this state for at least 300 ns , the parts are guaranteed to have entered shutdown. See Low-Power Shutdown Mode section.

### 3.3V-Powered, 10Mbps and Slew-Rate-Limited True RS-485/RS-422 Transceivers

Typical Operating Characteristics
$\left(\overline{\mathrm{V}} \mathrm{CC}=3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}\right.$, unless otherwise noted. $)$



OUTPUT CURRENT vs. DRIVER OUTPUT LOW VOLTAGE


OUTPUT CURRENT vs.
RECEIVER OUTPUT HIGH VOLTAGE


DRIVER OUTPUT CURRENT vs. DIFFERENTIAL OUTPUT VOLTAGE


RECEIVER OUTPUT HIGH VOLTAGE vs. TEMPERATURE


DRIVER DIFFERENTIAL OUTPUT VOLTAGE vs. TEMPERATURE


OUTPUT CURRENT vs. DRIVER OUTPUT HIGH VOLTAGE


### 3.3V-Powered, 10Mbps and Slew-Rate-Limited True RS-485/RS-422 Transceivers

Typical Operating Characteristics (continued)


TBMPERATURE $\left({ }^{\circ} \mathrm{C}\right)$ 100

vs. TEMPERATURE

Pin Description

| PIN |  |  | NAME |  |
| :---: | :---: | :---: | :---: | :--- |
| MAX3483/ <br> MAX3485/ <br> MAX3486 | MAX3488/ <br> MAX3490 | MAX3491 |  |  |

### 3.3V-Powered, 10Mbps and Slew-Rate-Limited True RS-485/RS-422 Transceivers



Figure 1. MAX3483/MAX3485/MAX3486 Pin Configuration and Typical Operating Circuit


Figure 2. MAX3488/MAX3490 Pin Configuration and Typical Operating Circuit


Figure 3. MAX3491 Pin Configuration and Typical Operating Circuit

### 3.3V-Powered, 10Mbps and Slew-Rate-Limited True RS-485/RS-422 Transceivers



Figure 4. Driver $V_{O D}$ and $V_{O C}$


Figure 6. Receiver $V_{O H}$ and $V_{O L}$


Figure 7. Driver Differential Output Delay and Transition Times

### 3.3V-Powered, 10Mbps and Slew-Rate-Limited True RS-485/RS-422 Transceivers



Figure 8. Driver Propagation Times


Figure 9. Driver Enable and Disable Times ( $t_{\text {PZH }}, t_{P S H}, t_{\text {PHZ }}$ )


Figure 10. Driver Enable and Disable Times ( $\left.t_{P Z L}, t_{P S L}, t_{P L Z}\right)$

### 3.3V-Powered, 10Mbps and Slew-Rate-Limited True RS-485/RS-422 Transc eivers



Figure 11. Receiver Propagation Delay


Figure 12. Receiver Enable and Disable Times

Note 4: The input pulse is supplied by a generator with the following characteristics: $\mathrm{PRR}=250 \mathrm{kHz}, 50 \%$ duty cycle, $\mathrm{tr} \leq 6.0 \mathrm{~ns}, \mathrm{ZO}_{\mathrm{O}}=50 \Omega$. Note 5: $C_{L}$ includes probe and stray capacitance.

# 3.3V-Powered, 10Mbps and Slew-Rate-Limited True RS-485/RS-422 Transceivers 

Function Tables

## Devices with Receiver/Driver Enable (MAX3483/MAX3485/MAX3486/MAX3491)

## Table 1. Transmitting

| INPUTS |  |  | OUTPUTS |  | MODE |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\overline{\mathbf{R E}}$ | $\mathbf{D E}$ | $\mathbf{D I}$ | $\mathbf{B}^{\boldsymbol{*}}$ | $\mathbf{A}^{*}$ |  |
| X | 1 | 1 | 0 | 1 | Normal |
| X | 1 | 0 | 1 | 0 | Normal |
| 0 | 0 | $X$ | High-Z | High-Z | Normal |
| 1 | 0 | $X$ | High-Z | High-Z | Shutdown |

* $B$ and $A$ outputs are $Z$ and $Y$, respectively, for full-duplex part (MAX3491).
$X=$ Don't care; High $-Z=$ High impedance


## Table 2. Receiving

| INPUTS |  |  | OUTPUTS | MODE |
| :---: | :---: | :---: | :---: | :---: |
| $\overline{\mathbf{R E}}$ | DE | A, B | RO |  |
| 0 | $0^{*}$ | $\geq+0.2 \mathrm{~V}$ | 1 | Normal |
| 0 | $0^{*}$ | $\leq-0.2 \mathrm{~V}$ | 0 | Normal |
| 0 | $0^{*}$ | Inputs Open | 1 | Normal |
| 1 | 0 | X | High-Z | Shutdown |

* DE is a "don't care" (x) for the full-duplex part (MAX3491). $X=$ Don't care; High $-Z=$ High impedance

Devices without Receiver/Driver Enable (MAX3488/MAX3490)

Table 3. Transmitting
Table 4. Receiving

| INPUT | OUTPUTS |  |
| :---: | :---: | :---: |
| DI | Z | Y |
| 1 | 0 | 1 |
| 0 | 1 | 0 |


| INPUTS | OUTPUT |
| :---: | :---: |
| $\mathrm{A}, \mathrm{B}$ | RO |
| $\geq+0.2 \mathrm{~V}$ | 1 |
| $\leq-0.2 \mathrm{~V}$ | 0 |
| Inputs Open | 1 |



Figure 13. Driver Output Waveform and FFT Plot of MAX3485/ MAX3490/MAX3491 Transmitting a 125kHz Signal

## Applications Information

The MAX3483/MAX3485/MAX3486/MAX3488/MAX3490/ MAX3491 are low-power transceivers for RS-485 and RS-422 communications. The MAX3483 and MAX3488 can transmit and receive at data rates up to 250 kbps , the MAX3486 at up to 2.5 Mbps , and the MAX3485/ MAX3490/MAX3491 at up to 10Mbps. The MAX3488/ MAX3490/MAX3491 are full-duplex transceivers, while the MAX3483/MAX3485/MAX3486 are half-duplex. Driver Enable (DE) and Receiver Enable (RE) pins are included on the MAX3483/MAX3485/MAX3486/ MAX3491. When disabled, the driver and receiver outputs are high impedance.

## Reduced EMI and Reflections <br> (MAX3483/MAX3486/MAX3488)

The MAX3483/MAX3488 are slew-rate limited, minimizing EMI and reducing reflections caused by improperly terminated cables. Figure 13 shows both the driver output waveform of a MAX3485/MAX3490/MAX3491 transmitting a 125 kHz signal and the Fourier analysis of that waveform. High-frequency harmonics with large amplitudes are evident. Figure 14 shows the same information, but for the slew-rate-limited MAX3483/MAX3488 transmitting the same signal. The high-frequency harmonics have much lower amplitudes, and the potential for EMI is significantly reduced.

## Low-Power Shutdown Mode

(MAX3483/MAX3485/MAX3486/MAX3491)
A low-power shutdown mode is initiated by bringing both $\overline{R E}$ high and DE low. The devices will not shut down unless both the driver and receiver are disabled (high impedance). In shutdown, the devices typically draw only 2 nA of supply current.
For these devices, the $t_{\text {PSH }}$ and $t_{\text {PSL }}$ enable times assume the part was in the low-power shutdown mode; the $t_{\text {PZH }}$ and $t_{\text {PZL }}$ enable times assume the receiver or driver was disabled, but the part was not shut down.


Figure 14. Driver Output Waveform and FFT Plot of MAX3483/ MAX3488 Transmitting a 125 kHz Signal

### 3.3V-Powered, 10Mbps and Slew-Rate-Limited True RS-485/RS-422 Transceivers



Figure 15. MAX3485/MAX3490/MAX3491 Driver Propagation Delay


Figure 17. MAX3483/MAX3488 Driver Propagation Delay


Figure 19. MAX3483/MAX3488 System Differential Voltage at 125 kHz Driving 4000 ft of Cable


Figure 16. MAX3485/MAX3490/MAX3491 Receiver Propagation Delay Driven by External RS-485 Device


Figure 18. MAX3483/MAX3488 Receiver Propagation Delay


Figure 20. MAX3485/MAX3490/MAX3491 System Differential Voltage at 125 kHz Driving 4000 ft of Cable

### 3.3V-Powered, 10Mbps and Slew-Rate-Limited True RS-485/RS-422 Transceivers



Figure 21. MAX3483/MAX3485/MAX3486 Typical RS-485 Network

## Driver Output Protection

Excessive output current and power dissipation caused by faults or by bus contention are prevented by two mechanisms. A foldback current limit on the output stage provides immediate protection against short circuits over the whole common-mode voltage range (see Typical Operating Characteristics). In addition, a thermal shutdown circuit forces the driver outputs into a high-impedance state if the die temperature rises excessively.

## Propagation Delay

Figures 15-18 show the typical propagation delays. Skew time is simply the difference between the low-to-high and high-to-low propagation delay. Small driver/receiver skew times help maintain a symmetrical mark-space ratio ( $50 \%$ duty cycle).
The receiver skew time, $\left.\right|_{\text {PRLL }}-\mathrm{t}_{\text {PRHL }} \mid$, is under 10 ns (20ns for the MAX3483/MAX3488). The driver skew times are 8ns for the MAX3485/MAX3490/MAX3491, 11 ns for the MAX3486, and typically under 100ns for the MAX3483/MAX3488.

Line Length vs. Data Rate The RS-485/RS-422 standard covers line lengths up to 4000 feet. For line lengths greater than 4000 feet, see Figure 23.
Figures 19 and 20 show the system differential voltage for parts driving 4000 feet of 26AWG twisted-pair wire at 125 kHz into $120 \Omega$ loads.

Typical Applications
The MAX3483, MAX3485, MAX3486, MAX3488, MAX3490, and MAX3491 transceivers are designed for bidirectional data communications on multipoint bus transmission lines. Figures 21 and 22 show typical network applications circuits. These parts can also be used as line repeaters, with cable lengths longer than 4000 feet, as shown in Figure 23.
To minimize reflections, the line should be terminated at both ends in its characteristic impedance, and stub lengths off the main line should be kept as short as possible. The slew-rate-limited MAX3483/MAX3488 and the partially slew-rate-limited MAX3486 are more tolerant of imperfect termination.

### 3.3V-Powered, 10Mbps and Slew-Rate-Limited True RS-485/RS-422 Transceivers



NOTE: REAND DE ON MAX3491 ONLY.

Figure 22. MAX3488/MAX3490/MAX3491 Full-Duplex RS-485 Network


Figure 23. Line Repeater for MAX3488/MAX3490/MAX3491

### 3.3V-Powered, 10Mbps and Slew-Rate-Limited True RS-485/RS-422 Transceivers

_Ordering Information (continued)

| PART | TEMP. RANGE | PIN-PACKAGE |
| :--- | ---: | :--- |
| MAX3486CPA | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | 8 Plastic DIP |
| MAX3486CSA | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | 8 SO |
| MAX3486C/D | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | Dice ${ }^{\star}$ |
| MAX3486EPA | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 8 Plastic DIP |
| MAX3486ESA | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 8 SO |
| MAX3488CPA | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | 8 Plastic DIP |
| MAX3488CSA | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | 8 SO |
| MAX3488C/D | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | Dice ${ }^{*}$ |
| MAX3488EPA | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 8 Plastic DIP |
| MAX3488ESA | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 8 SO |
| MAX3490CPA | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | 8 Plastic DIP |
| MAX3490CSA | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | 8 SO |
| MAX3490C/D | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | Dice ${ }^{*}$ |
| MAX3490EPA | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 8 Plastic DIP |
| MAX3490ESA | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 8 SO |
| MAX3491CPD | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | 14 Plastic DIP |
| MAX3491CSD | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | 14 SO |
| MAX3491C/D | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | Dice ${ }^{*}$ |
| MAX3491EPD | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 14 Plastic DIP |
| MAX3491ESD | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 14 SO |

* Contact factory for for dice specifications.


TRANSISTOR COUNT: 810
SUBSTRATE CONNECTED TO GROUND

### 3.3V-Powered, 10Mbps and Slew-Rate-Limited True RS-485/RS-422 Transceivers



Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.

16 $\qquad$ Maxim Integrated Products, 120 San Gabriel Drive, Sunnyvale, CA 94086 (408) 737-7600

