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[CC3200](http://www.ti.com/product/cc3200?qgpn=cc3200) SWAS032E –JULY 2013–REVISED JUNE 2014

CC3200 SimpleLink™ Wi-Fi® and Internet-of-Things Solution, a Single-Chip Wireless MCU

1 Device Overview

1.1 Features

- CC3200 SimpleLink Wi-Fi—Consists of Industry-Standard BSD Socket Application Applications Microcontroller, Wi-Fi Network Processor, and Power-Management Subsystems • 8 Simultaneous TCP or UDP Sockets
- - $-$ ARM[®] Cortex[®]-M4 Core at 80 MHz
	-
	-
	- Peripheral Drivers in ROM
Channel Direct Memory Access (uDMA) SimpleLink Connection Manager for
	-
	- Hardware Crypto Engine for Advanced Fast
		-
		-
		-
	- 8-Bit Parallel Camera Interface 14.5 dBm @ 54 OFDM
	- 1 Multichannel Audio Serial Port (McASP) ERX Sensitivity
Litterface with Support for Two I2S Channels 95.7 dBm @ 1 DSSS Interface with Support for Two I2S Channels
	-
	- 2 Universal Asynchronous Receivers and Power-Management Subsystem
	- 1 Serial Peripheral Interface (SPI)
	-
	- 4 General-Purpose Timers with 16-Bit Pulse- Preregulated 1.85-V Mode
	- 1 Watchdog Timer Hibernate: 4 µA
	- 4-Channel 12-Bit Analog-to-Digital Converters Low-Power Deep Sleep (LPDS): 120 µA (ADCs) • RX Traffic (MCU Active): 59 mA @
	- Up to 27 Individually Programmable, Multiplexed 54 OFDM GPIO Pins **• TX Traffic (MCU Active): 229 mA @**
- Wi-Fi Network Processor Subsystem 54 OFDM, Maximum Power
	-
	- Dedicated ARM MCU DTIM = 1 Completely Offloads Wi-Fi and Internet • Clock Source Protocols from the Application Microcontroller – 40.0-MHz Crystal with Internal Oscillator
	-
	- 802.11 b/g/n Radio, Baseband, Medium Access Package and Operating Temperature
	-
-
-
- Applications Microcontroller Subsystem 2 Simultaneous TLS and SSL Sockets
	- Powerful Crypto Engine for Fast, Secure Wi-Fi – Embedded Memory and Internet Connections with 256-Bit AES RAM (Up to 256KB) **Encryption for TLS and SSL Connections**
		- External Serial Flash Bootloader, and $-$ Station, AP, and Wi-Fi Direct[®] Modes
			-
	- 32-Channel Direct Memory Access (μDMA) – SimpleLink Connection Manager for
– Hardware Crynto Engine for Advanced East Autonomous and Fast Wi-Fi Connections
		- Security, Including SmartConfig™ Technology, AP Mode, and AES, DES, and 3DES
 $\begin{array}{r} \text{WPS2 for Easy and Flexible Wi-Fi Provisioning} \\ \text{SHA2 and MDE} \end{array}$
			-
			- TX Power SHA2 and MD5
			- e 18.0 dBm @ 1 DSSS
et Borellel Comerci Interface entity of the 14.5 dBm @ 54 OFDM
				- -
	- 1 SD/MMC Interface –74.0 dBm @ 54 OFDM
		-
		- Transmitters (UARTs)
1 Serial Peripheral Interface (SPI) $\begin{array}{c} \hbox{N} \\ \hbox{N} \end{array}$ Integrated DC-DC Supports a Wide Range of
	- $-$ 1 Inter-Integrated Circuit (I²C) \bullet V_{BAT} Wide-Voltage Mode: 2.1 to 3.6 V
		-
		- Advanced Low-Power Modes
			-
			-
			-
			-
	- Featuring Wi-Fi Internet-On-a-Chip™ Idle Connected (MCU in LPDS): 695 µA @
		- -
	- Wi-Fi and Internet Protocols in ROM 32.768-kHz Crystal or External RTC Clock
		-
	- Control (MAC), Wi-Fi Driver, and Supplicant 0.5-mm Pitch, 64-Pin, 9-mm x 9-mm QFN
Ambient Temperature Range: –40°C to 85
		- Ambient Temperature Range: -40° C to 85°C

1.2 Applications

- For Internet-of-Things applications, such as:
	- Cloud Connectivity Internet Gateway
	- Home Automation Industrial Control
	-
	-
	-
	- Smart Energy

1.3 Description

-
-
- Home Appliances Smart Plug and Metering
- Access Control Wireless Audio
- Security Systems IP Network Sensor Nodes

Start your design with the industry's first single-chip microcontroller unit (MCU) with built-in Wi-Fi connectivity. Created for the Internet of Things (IoT), the SimpleLink CC3200 device is a wireless MCU that integrates a high-performance ARM Cortex-M4 MCU, allowing customers to develop an entire application with a single IC. With on-chip Wi-Fi, Internet, and robust security protocols, no prior Wi-Fi experience is required for faster development. The CC3200 device is a complete platform solution including software, sample applications, tools, user and programming guides, reference designs, and the TI E2E™ support community. The device is available in a QFN package that is easy to layout.

The applications MCU subsystem contains an industry-standard ARM Cortex-M4 core running at 80 MHz. The device includes a wide variety of peripherals, including a fast parallel camera interface, I2S, SD/MMC, UART, SPI, I²C, and four-channel ADC. The CC3200 family includes flexible embedded RAM for code and data and ROM with external serial flash bootloader and peripheral drivers.

The Wi-Fi network processor subsystem features a Wi-Fi Internet-on-a-Chip and contains an additional dedicated ARM MCU that completely offloads the applications MCU. This subsystem includes an 802.11 b/g/n radio, baseband, and MAC with a powerful crypto engine for fast, secure Internet connections with 256-bit encryption. The CC3200 device supports Station, Access Point, and Wi-Fi Direct modes. The device also supports WPA2 personal and enterprise security and WPS 2.0. The Wi-Fi Internet-on-a-chip includes embedded TCP/IP and TLS/SSL stacks, HTTP server, and multiple Internet protocols.

The power-management subsystem includes integrated DC-DC converters supporting a wide range of supply voltages. This subsystem enables low-power consumption modes, such as the hibernate with RTC mode requiring less than 4 μA of current.

Device Information(1)

(1) For all available packages, see the orderable addendum at the end of the datasheet.

1.4 Functional Block Diagram

[Figure](#page-2-0) 1-1 shows the CC3200 hardware overview.

Figure 1-1. CC3200 Hardware Overview

[Figure](#page-2-1) 1-2 shows an overview of the CC3200 embedded software.

[Figure](#page-3-0) 1-3 shows a block diagram of the CC3200 device.

Figure 1-3. CC3200 Functional Block Diagram

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Table of Contents

2 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

3 Terminal Configuration and Functions

[Figure](#page-5-2) 3-1 shows pin assignments for the 64-pin QFN package.

Figure 3-1. QFN 64-Pin Assignments

3.1 Pin Attributes and Pin Multiplexing

The device makes extensive use of pin multiplexing to accommodate the large number of peripheral functions in the smallest possible package. To achieve this configuration, pin multiplexing is controlled using a combination of hardware configuration (at device reset) and register control.

NOTE

TI highly recommends using the CC3200 pin multiplexing utility to obtain the desired pinout.

The board and software designers are responsible for the proper pin multiplexing configuration. Hardware does not ensure that the proper pin multiplexing options are selected for the peripherals or interface mode used.

[Table](#page-7-0) 3-1 describes the general pin attributes and presents an overview of pin multiplexing. All pin multiplexing options are configurable using the pin mux registers.

The following special considerations apply:

- All I/Os support drive strengths of 2, 4, and 6 mA. Drive strength is configurable individually for each pin.
- All I/Os support 10-µA pullups and pulldowns.
- These pulls are not active and all of the I/Os remain floating while the device is in Hibernate state.
- The VIO and V_{BAT} supply must be tied together at all times.
- All digital I/Os are nonfail-safe.

NOTE

If an external device drives a positive voltage to the signal pads and the CC3200 device is not powered, DC current is drawn from the other device. If the drive strength of the external device is adequate, an unintentional wakeup and boot of the CC3200 device can occur. To prevent current draw, TI recommends any one of the following:

- All devices interfaced to the CC3200 device must be powered from the same power rail as the chip.
- Use level-shifters between the device and any external devices fed from other independent rails.
- The nRESET pin of the CC3200 device must be held low until the VBAT supply to the device is driven and stable.

Table 3-1. Pin Multiplexing

10 *Terminal Configuration and Functions* Copyright © 2013–2014, Texas Instruments Incorporated

(1) LPDS mode: The state of unused GPIOs in LPDS is input with 500 kΩ pulldown. For all used GPIOs , the user can enable internal pulls, which would hold them in a valid state.

(2) Hibernate mode: The CC3200 device leaves the digital pins in a Hi-Z state without any internal pulls when the device enters hibernate state. This can cause glitches on output lines unless held at valid levels by external resistors.

(3) To minimize leakage in some serial flash vendors during LPDS, TI recommends the user application always enable internal weak pulldowns on FLASH_SPI_DATA and FLASH_SPI_CLK pins.

(4) This pin has dual functions: as a SOP[2] (device operation mode), and as an external TCXO enable. As a TXCO enable, the pin is an output on power up and driven logic high. During hibernate low-power mode, the pin is in a high impedance state but pulled down for SOP mode to disable TCXO. Because of SOP functionality, the pin must be used as output only.

(5) Higher leakage current from the onboard serial flash can occur due to floating inputs when the device enters Hibernate mode. See reference schematics for recommended pull-up and pull-down resistors.

(6) For details on proper use, see [Section](#page-25-2) 3.2, *Drive Strength and Reset States for Analog-Digital Multiplexed Pins*.

(7) This pin is one of three that must have a passive pullup or pulldown resistor on board to configure the chip hardware power-up mode. Because of this reason, if this pin is used for digital functions, it must be output only.

(8) This pin is reserved for WLAN antenna selection, controlling an external RF switch that multiplexes the RF pin of the CC3200 device between two antennas. These pins should not be used for other functionalities in general.

- (9) Device firmware automatically enables the digital path during ROM boot.
- (10) Pin 45 is used by an internal DC-DC (ANA2_DCDC) and pin 52 is used by the RTC XTAL oscillator. These modules use automatic configuration sensing. Therefore, some board-level configuration is required to use pin 45 and pin 52 as digital pads (see [Figure](#page-20-6) 3-2). Because the CC3200R device does not require ANA2_DCDC, the pin can always be used for digital functions. However, pin 47 must be shorted to the supply input. Typically, pin 52 is used for RTC XTAL in most applications. However, in some applications a 32.768-kHz square-wave clock might always be available onboard. In such cases, the XTAL can be removed to free up pin 52 for digital functions. The external clock must then be applied at pin 51. For the chip to automatically detect this configuration, a 100K pull-up resistor must be connected between pin 52 and the supply line. To prevent false detection, TI recommends using pin 52 for outputonly functions.
- (11) VDD _{-FLASH} must be shorted to V_{supply}
- (12) To use the digital functions, RTC_XTAL_N must be pulled high to V_{supply} using 100-KΩ resistor.
- (13) This pin is shared by the ADC inputs and digital I/O pad cells. Important: The ADC inputs are tolerant up to 1.8 V. On the other hand, the digital pads can tolerate up to 3.6 V. Hence, care must be taken to prevent accidental damage to the ADC inputs. TI recommends that the output buffer(s) of the digital I/Os corresponding to the desired ADC channel be disabled first (that is, converted to high-impedance state), and thereafter the respective pass switches (S7, S8, S9, S10) should be enabled (see [Section](#page-25-2) 3.2, *Drive Strength and Reset States for Analog-Digital Multiplexed Pins*).
- (14) Requires user configuration to enable the ADC channel analog switch. (The switch is off by default.) The digital I/O is always connected and must be made Hi-Z before enabling the ADC switch.

Figure 3-2. Board Configuration to Use Pins 45 and 52 as Digital Signals

3.1.1 Connections for Unused Pins

All unused pins must be left as no connect (NC) pins. For a list of NC pins, see [Table](#page-21-0) 3-2.

Table 3-2. Connections for Unused Pins

3.1.2 Recommended Pin Multiplexing Configurations

[Table](#page-22-0) 3-3 lists the recommended pin multiplexing configurations.

Table 3-3. Recommended Pin Multiplexing Configurations

(1) Pins marked "wake" can be configured to wake up the chip from HIBERNATE or LPDS state. In the current silicon revision, any wake pin can trigger wake up from HIBERNATE. The wakeup monitor in the hibernate control module logically ORs these pins applying a selection mask. However, wakeup from LPDS state can be triggered only by one of the wakeup pins that can be configured before entering LPDS. The core digital wakeup monitor use a mux to select one of these pins to monitor.

(2) The device supports the feeding of an external 32.768-kHz clock. This configuration frees one pin (32K_XTAL_N) to use in output-only mode with a 100K pullup.

Table 3-3. Recommended Pin Multiplexing Configurations (continued)

3.2 Drive Strength and Reset States for Analog-Digital Multiplexed Pins

[Table](#page-25-3) 3-4 describes the use, drive strength, and default state of these pins at first-time power up and reset (nRESET pulled low).

Table 3-4. Drive Strength and Reset States for Analog-Digital Multiplexed Pins

3.3 Pad State After Application of Power To Chip But Prior To Reset Release

When a stable power is applied to the CC3200 chip for the first time or when supply voltage is restored to the proper value following a prior period with supply voltage below 1.5 V, the level of the digital pads are undefined in the period starting from the release of nRESET and until DIG_DCDC powers up. This period is less than approximately 10 ms. During this period, pads can be internally pulled weakly in either direction. If a certain set of pins are required to have a definite value during this pre-reset period, an appropriate pullup or pulldown must be used at the board level. The recommended value of this external pull is 2.7 KΩ.

4 Specifications

All measurements are referenced at the device pins, unless otherwise indicated. All specifications are over process and voltage, unless otherwise indicated.

4.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)

4.2 Handling Ratings

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

4.3 Power-On Hours

(1) The CC3200 device can be operated reliably for 10 years.

4.4 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted) (1)

(1) Operating temperature is limited by crystal frequency variation.

(2) To ensure WLAN performance, ripple on the 2.1- to 3.3-V supply must be less than ±300 mV.

(3) To ensure WLAN performance, ripple on the 1.85-V supply must be less than 2% (±40 mV).

The device enters a brown-out condition whenever the input voltage dips below V_{BROWN} (see [Figure](#page-27-1) 4-1). This condition must be considered during design of the power supply routing, especially if operating from a battery. High-current operations (such as a TX packet) cause a dip in the supply voltage, potentially triggering a brownout. The resistance includes the internal resistance of the battery, contact resistance of the battery holder (4 contacts for a 2 x AA battery) and the wiring and PCB routing resistance.

Note: For V_{BAT} wide-voltage mode, $V_{BROWN} = 2.1$ V. For preregulated 1.85-V mode, $V_{BROWN} = 1.76$ V.

Figure 4-1. Brown-Out Timing Diagram

For example, the device draws about 400 mA from the supply @ 2.3 V for a 1 DSSS packet at maximum power. This condition can cause a drop of 200 mV across a 0.5-Ω routing resistance.

In the brown-out condition, the device is in RESET state except for the Hibernate module (including the 32-kHz RTC clock), which is kept on. The current in this state can reach approximately 400 µA.

4.5 Electrical Characteristics

3.3 V, 25°C

(1) TI recommends using the lowest possible drive strength that is adequate for the applications. This recommendation minimizes the risk of interference to the WLAN radio and mitigates any potential degradation of RF sensitivity and performance. The default drive strength setting is 6 mA.

3.3 V, 25°C

(1) TI recommends using the lowest possible drive strength that is adequate for the applications. This recommendation minimizes the risk of interference to the WLAN radio and mitigates any potential degradation of RF sensitivity and performance. The default drive strength setting is 6 mA.

3.3 V, 25°C

Pin Internal Pullup and Pulldown (25°C)(1)

(1) TI recommends using the lowest possible drive strength that is adequate for the applications. This recommendation minimizes the risk of interference to WLAN radio and mitigates any potential degradation of RF sensitivity and performance. The default drive-strength setting is 6 mA.

4.6 WLAN Receiver Characteristics

 T_A = +25°C, V_{BAT} = 2.1 to 3.6 V. Parameters measured at SoC pin on channel 7 (2442 MHz)

(1) Sensitivity is 1-dB worse on channel 13 (2472 MHz).

(2) Sensitivity for mixed mode is 1-dB worse.

4.7 WLAN Transmitter Characteristics

(1) Channel-to-channel variation is up to 2 dB. The edge channels (2412 and 2472 MHz) have reduced TX power to meet FCC emission limits.

(2) In preregulated 1.85-V mode, maximum TX power is 0.25 to 0.75 dB lower for modulations higher than 18 OFDM.

4.8 Current Consumption

 $T_A = +25$ °C, $V_{BAT} = 3.6 V$

- (2) The CC3200 system is a constant power-source system. The active current numbers scale based on the V_{BAT} voltage supplied.
(3) DTIM = 1 $DTIM = 1$
-

⁽¹⁾ TX power level = 0 implies maximum power (see [Figure](#page-30-0) 4-2 through [Figure](#page-31-0) 4-4). TX power level = 4 implies output power backed off approximately 4 dB.

Current Consumption *(continued)*

(4) LPDS current does not include the external serial flash. The LPDS number reported is with retention of 64KB MCU SRAM. The CC3200 device can be configured to retain 0KB, 64KB, 128KB, 192KB or 256KB SRAM in LPDS. Each 64KB retained increases LPDS current by 4μ A.

Serial flash current consumption in power-down mode during hibernate is not included.

(6) The complete calibration can take up to 17 mJ of energy from the battery over a time of 24 ms . Calibration is performed sparingly, typically when coming out of Hibernate and only if temperature has changed by more than 20°C or the time elapsed from prior calibration is greater than 24 hours.

level 3 to 4. In the case of lower range requirements (14 dbm output power), TI recommends using TX power level 4 to reduce the current.

Figure 4-2. TX Power and IBAT vs TX Power Level Settings (1 DSSS)

Figure 4-4. TX Power and IBAT vs TX Power Level Settings (54 OFDM)

4.9 Thermal Characteristics for RGC Package

4.10 Timing and Switching Characteristics

4.10.1 Power Supply Sequencing

For proper operation of the CC3200 device, perform the recommended power-up sequencing as follows:

- 1. Tie V_{BAT} (pins 37, 39, 44) and V_{IO} (pins 54 and 10) together on the board.
- 2. Hold the RESET pin low while the supplies are ramping up. TI recommends using a simple RC circuit (100K || $0.1 \mu F$, RC = 10 ms).
- 3. For an external RTC clock, ensure that the clock is stable before RESET is deasserted (high).

For timing diagrams, see [Section](#page-32-2) 4.10.2, *Reset Timing*.

4.10.2 Reset Timing

4.10.2.1 nRESET (32K XTAL)

[Figure](#page-32-3) 4-5 shows the reset timing diagram for the 32K XTAL first-time power-up and reset removal.

Figure 4-5. First-Time Power-Up and Reset Removal Timing Diagram (32K XTAL)

[Table](#page-33-0) 4-1 describes the timing requirements for the 32K XTAL first-time power-up and reset removal.

Table 4-1. First-Time Power-Up and Reset Removal Timing Requirements (32K XTAL)

4.10.2.2 nRESET (External 32K)

[Figure](#page-33-1) 4-6 shows the reset timing diagram for the external 32K first-time power-up and reset removal.

32.768 KHz **External Clock**

Figure 4-6. First-Time Power-Up and Reset Removal Timing Diagram (External 32K)

[Table](#page-33-2) 4-2 describes the timing requirements for the external 32K first-time power-up and reset removal.

Item	Name	Description	Min	Typ	Max
T ₁	Supply settling time	Depends on application board power supply, decap, and so on		3 ms	
T ₂	Hardware wakeup time			25 ms	
T ₃	Time taken by ROM firmware to initialize hardware	Time taken by ROM firmware		3 ms	

Table 4-2. First-Time Power-Up and Reset Removal Timing Requirements (External 32K)

4.10.2.3 Wakeup from Hibernate

[Figure](#page-34-0) 4-7 shows the timing diagram for wakeup from the hibernate state.

32KHz <u> NOON OO DAADDA DAADDA DAADDA DAADDA DAADDA DAADDA DAADDA DAADDA DAADDA DA</u> **XTAL/CXO**

Figure 4-7. nHIB Timing Diagram

NOTE

The 32.768-kHz XTAL is kept enabled by default when the chip goes to hibernate.

[Table](#page-34-1) 4-3 describes the timing requirements for nHIB.

Table 4-3. Software Hibernate Timing Requirements

(1) Twake_from_hib can be 200 ms on rare occasions when calibration is performed. Calibration is performed sparingly, typically when exiting Hibernate and only if temperature has changed by more than 20°C or more than 24 hours have elapsed since a prior calibration.

4.10.3 Clock Specifications

The CC3200 device requires two separate clocks for its operation:

- A slow clock running at 32.768 kHz is used for the RTC.
- A fast clock running at 40 MHz is used by the device for the internal processor and the WLAN subsystem.

The device features internal oscillators that enable the use of cheaper crystals rather than dedicated TCXOs for these clocks. The RTC can also be fed externally to provide reuse of an existing clock on the system and reduce overall cost.

4.10.3.1 Slow Clock Using Internal Oscillator

The RTC crystal connected on the device supplies the free-running slow clock. The accuracy of the slow clock frequency must be 32.768 kHz ±150 ppm. In this mode of operation, the crystal is tied between RTC_XTAL_P (pin 51) and RTC_XTAL_N (pin 52) with a suitable load capacitance.

[Figure](#page-35-0) 4-8 shows the crystal connections for the slow clock.

Figure 4-8. RTC Crystal Connections

4.10.3.2 Slow Clock Using an External Clock

When an RTC clock oscillator is present in the system, the CC3200 device can accept this clock directly as an input. The clock is fed on the RTC_XTAL_P line and the RTC_XTAL_N line is held to VIO. The clock must be a CMOS-level clock compatible with VIO fed to the device.

[Figure](#page-35-1) 4-9 shows the external RTC clock input connection.

Figure 4-9. External RTC Clock Input

4.10.3.3 Fast Clock (Fref) Using an External Crystal

The CC3200 device also incorporates an internal crystal oscillator to support a crystal-based fast clock. The XTAL is fed directly between WLAN_XTAL_P (pin 23) and WLAN_XTAL_N (pin 22) with suitable loading capacitors.

[Figure](#page-36-0) 4-10 shows the crystal connections for the fast clock.

Figure 4-10. Fast Clock Crystal Connections

4.10.3.4 Fast Clock (Fref) Using an External Oscillator

The CC3200 device can accept an external TCXO/XO for the 40-MHz clock. In this mode of operation, the clock is connected to WLAN_XTAL_P (pin 23). WLAN_XTAL_N (pin 22) is connected to GND. The external TCXO/XO can be enabled by TCXO_EN (pin 21) from the device to optimize the power consumption of the system.

If the TCXO does not have an enable input, an external LDO with an enable function can be used. Using the LDO improves noise on the TCXO power supply.

[Figure](#page-36-0) 4-11 shows the connection.

Figure 4-11. External TCXO Input

[Table](#page-36-1) 4-4 lists the external F_{ref} clock requirements.

4.10.3.5 Input Clocks/Oscillators

[Table](#page-37-0) 4-5 lists the RTC crystal requirements.

Table 4-5. RTC Crystal Requirements

[Table](#page-37-1) 4-6 lists the external RTC digital clock requirements.

Table 4-6. External RTC Digital Clock Requirements

[Table](#page-37-2) 4-7 lists the WLAN fast-clock crystal requirements.

Table 4-7. WLAN Fast-Clock Crystal Requirements

4.10.4 Peripherals

This section describes the peripherals that are supported by the CC3200 device:

- SPI
- McASP
- GPIO
- I^2C
- IEEE 1149.1 JTAG
- ADC
- Camera parallel port
- UART

4.10.4.1 SPI

4.10.4.1.1 SPI Master

The CC3200 microcontroller includes one SPI module, which can be configured as a master or slave device. The SPI includes a serial clock with programmable frequency, polarity, and phase, a programmable timing control between chip select and external clock generation, and a programmable delay before the first SPI word is transmitted. Slave mode does not include a dead cycle between two successive words.

[Figure](#page-38-0) 4-12 shows the timing diagram for the SPI master.

Figure 4-12. SPI Master Timing Diagram

[Table](#page-38-1) 4-8 lists the timing parameters for the SPI master.

Table 4-8. SPI Master Timing Parameters

(1) Timing parameter assumes a maximum load of 20 pF.

4.10.4.1.2 SPI Slave

[Figure](#page-38-2) 4-13 shows the timing diagram for the SPI slave.

Figure 4-13. SPI Slave Timing Diagram

[Table](#page-39-0) 4-9 lists the timing parameters for the SPI slave.

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Table 4-9. SPI Slave Timing Parameters

(1) Timing parameter assumes a maximum load of 20 pF at 3.3 V.

4.10.4.2 McASP

The McASP interface functions as a general-purpose audio serial port optimized for multichannel audio applications and supports transfer of two stereo channels over two data pins. The McASP consists of transmit and receive sections that operate synchronously and have programmable clock and frame-sync polarity. A fractional divider is available for bit-clock generation.

4.10.4.2.1 I2S Transmit Mode

[Figure](#page-39-1) 4-14 shows the timing diagram for the I2S transmit mode.

Figure 4-14. I2S Transmit Mode Timing Diagram

[Table](#page-39-2) 4-10 lists the timing parameters for the I2S transmit mode.

(1) Timing parameter assumes a maximum load of 20 pF.

4.10.4.2.2 I2S Receive Mode

[Figure](#page-40-0) 4-15 shows the timing diagram for the I2S receive mode.

[Table](#page-40-1) 4-11 lists the timing parameters for the I2S receive mode.

(1) Timing parameter assumes a maximum load of 20 pF.

4.10.4.3 GPIO

All digital pins of the device can be used as general-purpose input/output (GPIO) pins.The GPIO module consists of four GPIO blocks, each of which provides eight GPIOs. The GPIO module supports 24 programmable GPIO pins, depending on the peripheral used. Each GPIO has configurable pullup and pulldown strength (weak 10 µA), configurable drive strength (2, 4, and 6 mA), and open-drain enable.

[Figure](#page-40-2) 4-16 shows the GPIO timing diagram.

Figure 4-16. GPIO Timing

4.10.4.3.1 GPIO Output Transition Time Parameters (Vsupply = 3.3 V)

[Table](#page-41-0) 4-12 lists the GPIO output transition times for $V_{\text{supply}} = 3.3$ V.

Drive	Drive Strength Control Bits	T_r (ns)			T_f (ns)		
Strength (mA)		Min	Nom	Max	Min	Nom	Max
$\mathbf 2$	2MA_EN=1						
	4MA_EN=0	8.0	9.3	10.7	8.2	9.5	11.0
	8MA_EN=0						
$\overline{4}$	2MA EN=0						
	4MA EN=1	6.6	7.1	7.6	4.7	5.2	5.8
	8MA_EN=0						
8	2MA_EN=0						
	4MA_EN=0	3.2	3.5	3.7	2.3	2.6	2.9
	8MA_EN=1						
14	2MA_EN=1						
	4MA_EN=1	1.7	1.9	2.0	1.3	1.5	1.6
	8MA_EN=1						

Table 4-12. GPIO Output Transition Times (Vsupply = 3.3 V)(1)(2)

(1) V_{supply} = 3.3 V, T = 25°C, total pin load = 30 pF
(2) The transition data applies to the pins other than the multiplexed analog-digital pins 29, 30, 45, 50, 52, and 53.

4.10.4.3.2 GPIO Output Transition Time Parameters (Vsupply = 1.8 V)

[Table](#page-41-1) 4-13 lists the GPIO output transition times for $V_{\text{supply}} = 1.8$ V.

Drive	Drive Strength Control Bits	T_r (ns)			T_f (ns)		
Strength (mA)		Min	Nom	Max	Min	Nom	Max
$\overline{2}$	2MA_EN=1						
	4MA_EN=0	11.7	13.9	16.3	11.5	13.9	16.7
	8MA_EN=0						
$\overline{\mathbf{4}}$	2MA EN=0	13.7	15.6	18.0	9.9	11.6	13.6
	4MA_EN=1						
	8MA EN=0						
8	2MA_EN=0	5.5	6.4	7.4	3.8	4.7	5.8
	4MA_EN=0						
	8MA_EN=1						
14	2MA_EN=1						
	4MA EN=1	2.9	3.4	4.0	2.2	2.7	3.3
	8MA EN=1						

Table 4-13. GPIO Output Transition Times (Vsupply = 1.8 V)(1)(2)

(1) V_{supply} = 1.8 V, T = 25°C, total pin load = 30 pF
(2) The transition data applies to the pins other than the multiplexed analog-digital pins 29, 30, 45, 50, 52, and 53.

4.10.4.3.3 GPIO Input Transition Time Parameters

[Table](#page-41-2) 4-14 lists the input transition time parameters.

4.10.4.4 I 2C

The CC3200 microcontroller includes one I^2C module operating with standard (100 Kbps) or fast (400 Kbps) transmission speeds.

[Figure](#page-42-0) 4-17 shows the I^2C timing diagram.

[Table](#page-42-1) 4-15 lists the I^2C timing parameters.

(1) All timing is with 6-mA drive and 20-pF load.
(2) This value depends on the value programme (2) This value depends on the value programmed in the clock period register of l^2C . Maximum output frequency is the result of the minimal value programmed in this register.

(3) Because I²C is an open-drain interface, the controller can drive logic 0 only. Logic is the result of external pullup. Rise time depends on the external signal capacitance and external pullup register value.

4.10.4.5 IEEE 1149.1 JTAG

The Joint Test Action Group (JTAG) port is an IEEE standard that defines a test access port (TAP) and boundary scan architecture for digital integrated circuits and provides a standardized serial interface to control the associated test logic. For detailed information on the operation of the JTAG port and TAP controller, see the IEEE Standard 1149.1,*Test Access Port and Boundary- Scan Architecture*.

[Figure](#page-43-0) 4-18 shows the JTAG timing diagram.

Figure 4-18. JTAG Timing

[Table](#page-43-1) 4-16 lists the JTAG timing parameters.

Table 4-16. JTAG Timing Parameters

Parameter Number	Parameter	Parameter Name	Min	Max	Unit
J1	fTCK	Clock frequency		15	MHz
J2	tTCK	Clock period		1/fTCK	ns
J3	tCL	Clock low period		tTCK/2	ns
J4	tCH	Clock high period		tTCK/2	ns
J7	tTMS_SU	TMS setup time			
J8	tTMS_HO	TMS hold time	16		
J9	tTDI_SU	TDI setup time			
J10	tTDI HO	TDI hold time	16		
J11	tTDO_HO	TDO hold time		15	

4.10.4.6 ADC

[Table](#page-43-2) 4-17 lists the ADC electrical specifications.

[Figure](#page-44-0) 4-19 shows the ADC clock timing diagram.

Figure 4-19. ADC Clock Timing

4.10.4.7 Camera Parallel Port

The fast camera parallel port interfaces with a variety of external image sensors, stores the image data in a FIFO, and generates DMA requests. The camera parallel port supports 8 bits.

[Figure](#page-44-1) 4-20 shows the timing diagram for the camera parallel port.

Figure 4-20. Camera Parallel Port Timing Diagram

[Table](#page-44-2) 4-18 lists the timing parameters for the camera parallel port.

4.10.4.8 UART

The CC3200 device includes two UARTs with the following features:

- Programmable baud-rate generator allowing speeds up to 3 Mbps
- Separate 16 x 8 TX and RX FIFOs to reduce CPU interrupt service loading
- Programmable FIFO length, including 1-byte deep operation providing conventional double-buffered interface
- FIFO trigger levels of 1/8, 1/4, 1/2, 3/4, and 7/8
- Standard asynchronous communication bits for start, stop, and parity
- Line-break generation and detection
- Fully programmable serial interface characteristics
	- $-$ 5, 6, 7, or 8 data bits
	- Even, odd, stick, or no-parity bit generation and detection
	- 1 or 2 stop-bit generation
- RTS and CTS hardware flow support
- Standard FIFO-level and End-of-Transmission interrupts
- Efficient transfers using μDMA
	- Separate channels for transmit and receive
	- Receive single request asserted when data is in the FIFO; burst request asserted at programmed FIFO level
	- Transmit single request asserted when there is space in the FIFO; burst request asserted at programmed FIFO level
- System clock is used to generate the baud clock.

5 Detailed Description

5.1 Overview

The CC3200 device has a rich set of peripherals for diverse application requirements. The device optimizes bus matrix and memory management to give the application developer the needed advantage. This section briefly highlights the internal details of the CC3200 device and offers suggestions for application configurations.

5.1.1 Device Features

5.2 Functional Block Diagram

[Figure](#page-46-0) 5-1 shows the functional block diagram of the CC3200 SimpleLink Wi-Fi solution.

Figure 5-1. Functional Block Diagram

5.3 ARM Cortex-M4 Processor Core Subsystem

The high-performance ARM Cortex-M4 processor provides a low-cost platform that meets the needs of minimal memory implementation, reduced pin count, and low power consumption, while delivering outstanding computational performance and exceptional system response to interrupts.

- The ARM Cortex-M4 core has low-latency interrupt processing with the following features:
	- A 32-bit ARM Cortex Thumb® instruction set optimized for embedded applications
	- Handler and thread modes
	- Low-latency interrupt handling by automatic processor state saving and restoration during entry and exit
	- Support for ARMv6 unaligned accesses
- Nested vectored interrupt controller (NVIC) closely integrated with the processor core to achieve low latency interrupt processing. Features include:
	- Bits of priority configurable from 3 to 8
	- Dynamic reprioritization of interrupts
	- Priority grouping that enables selection of preempting interrupt levels and nonpreempting interrupt levels
	- Support for tail-chaining and late arrival of interrupts, which enables back-to-back interrupt processing without the overhead of state saving and restoration between interrupts
	- Processor state automatically saved on interrupt entry and restored on interrupt exit with no instruction overhead
	- Wake-up interrupt controller (WIC) providing ultra-low power sleep mode support
- Bus interfaces:
	- Three advanced high-performance bus (AHB-Lite) interfaces: ICode, DCode, and system bus interfaces
	- Bit-band support for memory and select peripheral that includes atomic bit-band write and read operations
- Low-cost debug solution featuring:
	- Debug access to all memory and registers in the system, including access to memory-mapped devices, access to internal core registers when the core is halted, and access to debug control registers even while SYSRESETn is asserted
	- Serial wire debug port (SW-DP) or serial wire JTAG debug port (SWJ-DP) debug access
	- Flash patch and breakpoint (FPB) unit to implement breakpoints and code patches

5.4 CC3200 Device Encryption

[Figure](#page-47-0) 5-2 shows a standard MCU for the CC3200 device. Application image and user data files are not encrypted. Network certificates are encrypted using a device-specific key.

5.5 Wi-Fi Network Processor Subsystem

The Wi-Fi network processor subsystem includes a dedicated ARM MCU to completely offload the host MCU along with an 802.11 b/g/n radio, baseband, and MAC with a powerful crypto engine for a fast, secure WLAN and Internet connections with 256-bit encryption. The CC3200 device supports station, AP, and Wi-Fi Direct modes. The device also supports WPA2 personal and enterprise security and WPS 2.0. The Wi-Fi network processor includes an embedded IPv4 TCP/IP stack.

[Table](#page-48-0) 5-1 summarizes the NWP features.

5.6 Power-Management Subsystem

The CC3200 power-management subsystem contains DC-DC converters to accommodate the differing voltage or current requirements of the system.

- Digital DC-DC
	- Input: VBAT wide voltage (2.1 to 3.6 V) or preregulated 1.85 V
- ANA1 DC-DC
	- Input: VBAT wide voltage (2.1 to 3.6 V)
	- In preregulated 1.85-V mode, the ANA1 DC-DC converter is bypassed.
- PA DC-DC
	- Input: VBAT wide voltage (2.1 to 3.6 V)
	- In preregulated 1.85-V mode, the PA DC-DC converter is bypassed.

In preregulated 1.85-V mode, the ANA1 DC-DC and PA DC-DC converters are bypassed. The CC3200 device is a single-chip WLAN radio solution used on an embedded system with a wide-voltage supply range. The internal power management, including DC-DC converters and LDOs, generates all of the voltages required for the device to operate from a wide variety of input sources. For maximum flexibility, the device can operate in the modes described in the following sections.

5.6.1 VBAT Wide-Voltage Connection

In the wide-voltage battery connection, the device is powered directly by the battery or preregulated 3.3-V supply. All other voltages required to operate the device are generated internally by the DC-DC converters. This scheme is the most common mode for the device as it supports wide-voltage operation from 2.1 to 3.6 V (for electrical connections, see [Section](#page-56-0) 6.1.1, *Typical Application – CC3200 Wide-Voltage Mode*).

5.6.2 Preregulated 1.85 V

The preregulated 1.85-V mode of operation applies an external regulated 1.85 V directly at the pins 10, 25, 33, 36, 37, 39, 44, 48, and 54 of the device. The VBAT and the VIO are also connected to the 1.85-V supply. This mode provides the lowest BOM count version in which inductors used for PA DC-DC and ANA1 DC-DC (2.2 and 1 μ H) and a capacitor (22 μ F) can be avoided. For electrical connections, see [Section](#page-58-0) 6.1.2, *Typical Application – CC3200 Preregulated 1.85-V Mode*.

In the preregulated 1.85-V mode, the regulator providing the 1.85 V must have the following characteristics:

- Load current capacity ≥900 mA.
- Line and load regulation with <2% ripple with 500 mA step current and settling time of <4 µs with the load step.
- The regulator must be placed very close to the CC3200 device so that the IR drop to the device is very low.

5.7 Low-Power Operating Mode

From a power-management perspective, the CC3200 device comprises the following two independent subsystems:

- Cortex-M4 application processor subsystem
- Networking subsystem

Each subsystem operates in one of several power states.

The Cortex-M4 application processor runs the user application loaded from an external serial flash. The networking subsystem runs preprogrammed TCP/IP and Wi-Fi data link layer functions.

The user program controls the power state of the application processor subsystem and can be in one of the five modes described in [Table](#page-50-0) 5-2.

NOTE

[Table](#page-50-0) 5-2 lists the modes by power consumption, with highest power modes listed first.

Table 5-2. User Program Modes

The NWP can be active or in LPDS mode and takes care of its own mode transitions. When there is no network activity, the NWP sleeps most of the time and wakes up only for beacon reception.

Table 5-3. Networking Subsystem Modes

The operation of the application and network processor ensures that the device remains in the lowest power mode most of the time to preserve battery life. [Table](#page-50-1) 5-4 summarizes the important CC3200 chiplevel power modes.

The following examples show the use of the power modes in applications:

- A product that is continuously connected to the network in the 802.11 infrastructure power-save mode but sends and receives little data spends most of the time in connected idle, which is a composite of modes A (receiving a beacon frame) and B (waiting for the next beacon).
- A product that is not continuously connected to the network but instead wakes up periodically (for example, every 10 minutes) to send data spends most of the time in mode D (hibernate), jumping briefly to mode C (active) to transmit data.

5.8 Memory

5.8.1 External Memory Requirements

The CC3200 device maintains a proprietary file system on the SFLASH. The CC3200 file system stores the service pack file, system files, configuration files, certificate files, web page files, and user files. By using a format command through the API, users can provide the total size allocated for the file system. The starting address of the file system cannot be set and is always located at the beginning of the SFLASH. The applications microcontroller must access the SFLASH memory area allocated to the file system directly through the CC3200 file system. The applications microcontroller must not access the SFLASH memory area directly.

The file system manages the allocation of SFLASH blocks for stored files according to download order, which means that the location of a specific file is not fixed in all systems. Files are stored on SFLASH using human-readable file names rather than file IDs. The file system API works using plain text, and file encryption and decryption is invisible to the user. Encrypted files can be accessed only through the file system (see [Figure](#page-47-0) 5-2).

All file types can have a maximum of 128 supported files in the file system. All files are stored in blocks of 4KB and thus use a minimum of 4KB of flash space. Encrypted files with fail-safe support and optional security are twice the original size and use a minimum of 8KB. Encrypted files are counted as fail safe in terms of space. The maximum file size is 16MB.

[Table](#page-51-0) 5-5 lists the SFLASH size recommendations.

Table 5-5. CC3200 SFLASH Size Recommendations

The CC3200 device supports JEDEC specification SFDP (serial flash device parameters). The following SFLASH devices are verified for functionality with the CC3200 device in addition to the ones in the reference design:

- Micron (N25Q128-A13BSE40): 128Mb
- Spansion (S25FL208K): 8Mb
- Winbond (W25Q16V): 16Mb
- Adesto (AT25DF081A): 8Mb
- Macronix (MX25L12835F-M2): 128Mb

For compatibility with the CC3200 device, the SFLASH device must support the following commands:

- Command 0x9F (read the device ID [JEDEC]). Procedure: SEND 0x9F, READ 3 bytes.
- Command 0x05 (read the status of the SFLASH). Procedure: SEND 0x05, READ 1 byte. Assume bit 0 is busy and bit 1 is write enable.
- Command 0x06 (set write enable). Procedure: SEND 0x06, read status until write-enable bit is set.
- Command 0xC7 (chip erase). Procedure: SEND 0xC7, read status until busy bit is cleared.
- Command 0x03 (read data). Procedure: SEND 0x03, SEND 24-bit address, read *n* bytes.
- Command 0x02 (write page). Procedure: SEND 0x02, SEND 24-bit address, write *n* bytes (0<*n*<256).
- Command 0x20 (sector erase). Procedure: SEND 0x20, SEND 24-bit address, read status until busy bit is cleared. Sector size is assumed to be always 4K.

5.8.2 Internal Memory

The CC3200 device includes on-chip SRAM to which application programs are downloaded and executed. The application developer must share the SRAM for code and data. To select the appropriate SRAM configuration, see the device variants listed in the orderable addendum at the end of this datasheet. The micro direct memory access (μDMA) controller can transfer data to and from SRAM and various peripherals. The CC3200 ROM holds the rich set of peripheral drivers, which saves SRAM space. For more information on drivers, see the CC3200 API list.

5.8.2.1 SRAM

The CC3200 family provides up to 256KB of zero-wait-state, on-chip SRAM. Internal RAM is capable of selective retention during LPDS mode. This internal SRAM is located at offset 0x2000 0000 of the device memory map.

Use the μ DMA controller to transfer data to and from the SRAM.

When the device enters low-power mode, the application developer can choose to retain a section of memory based on need. Retaining the memory during low-power mode provides a faster wakeup. The application developer can choose the amount of memory to retain in multiples of 64KB. For more information, see the API guide.

5.8.2.2 ROM

The internal zero-wait-state ROM of the CC3200 device is at address 0x0000 0000 of the device memory and programmed with the following components:

- Bootloader
- Peripheral driver library (DriverLib) release for product-specific peripherals and interfaces

The bootloader is used as an initial program loader (when the serial flash memory is empty). The CC3200 DriverLib software library controls on-chip peripherals with a bootloader capability. The library performs peripheral initialization and control functions, with a choice of polled or interrupt-driven peripheral support. The DriverLib APIs in ROM can be called by applications to reduce flash memory requirements and free the flash memory to be used for other purposes.

5.8.2.3 Memory Map

[Table](#page-52-0) 5-6 describes the various MCU peripherals and how they are mapped to the processor memory. For more information on peripherals, see the API document.

Table 5-6. Memory Map

5.9 Boot Modes

5.9.1 Overview

The boot process of the application processor includes two phases. The first phase consists of unrestricted access to all register space and configuration of the specific device setting. In the second phase, the application processor executes user-specific code.

[Figure](#page-54-0) 5-3 shows the bootloader flow chart.

Note: For definitions of the SoP mode functional configurations, see [Table](#page-55-0) 5-7.

Figure 5-3. Bootloader Flow Chart

5.9.2 Invocation Sequence/Boot Mode Selection

The following sequence of events occur during the Cortex processor boot:

- 1. After power-on-reset (POR), the processor starts execution.
- 2. The processor jumps to the first few lines (FFL) of code in the ROM to determine if the current boot is the first device-init boot or the second MCU boot. The determination is based on the Device-Init flag in a secure register. The Device-Init flag is set out of POR. The registers in the secure region are accessible only in the device-init mode.
- 3. If the current boot is the first boot, the processor executes the device-init code from ROM.
- 4. At the end of the boot, the processor clears the Device-Init flag and changes the master ID of the processor and the DMA. These registers are part of the secure region.
- 5. The processor resets itself, initiating a second boot.
- 6. During the second boot, the processor rereads the Device-Init flag, the bit is cleared, and the processor obtains a different master ID.
- 7. After executing FFL and the unsecure boot code, the processor jumps to the developer code (application).
- 8. For the rest of the operation (until the next power cycle), the Cortex mode is designated the MCU. During this phase, access to the secure region is restricted.

5.9.3 Boot Mode List

The CC3200 device implements a sense-on-power (SoP) scheme to determine the device operation mode. The device can be configured to power up in one of the three following modes:

- Fn4WJ: Functional mode with a 4-wire JTAG mapped to fixed pins.
- Fn2WJ: Functional mode with a 2-wire SWD mapped to fixed pins.
- LDfrUART: UART load mode to flash the system during development and in OEM assembly line (for example, serial flash connected to the CC3200R device).

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SoP values are sensed from the device pin during power up. This encoding determines the boot flow. Before the device is taken out of reset, the SoP values are copied to a register and then determine the device opeartion mode while powering up. These values determine the boot flow as well as the default mapping for some of the pins (JTAG, SWD, UART0) [Table](#page-55-0) 5-7 show the pull configurations.

Table 5-7. CC32x0 Functional Configurations

The recommended value of pull resistors for SOP0 and SOP1 is 100 kΩ and 2.7 kΩ for SOP2. SOP2 can be used by the application for other functions after chip power-up is complete. However, to avoid spurious SOP values from being sensed at power-up, TI strongly recommends that the SOP2 pin be used only for output signals. On the other hand, the SOP0 and SOP1 pins are multiplexed with WLAN analog test pins and are not available for other functions.

6 Applications and Implementation

6.1 Application Information

6.1.1 Typical Application – CC3200 Wide-Voltage Mode

[Figure](#page-56-1) 6-1 shows the schematics for an application using the CC3200 wide-voltage mode.

Figure 6-1. Schematics for CC3200 Wide-Voltage Mode Application

[Table](#page-57-0) 6-1 lists the bill of materials for an application using the CC3200 wide-voltage mode.

Table 6-1. Bill of Materials for CC3200 Wide-Voltage Mode Application

6.1.2 Typical Application – CC3200 Preregulated 1.85-V Mode

[Figure](#page-58-1) 6-2 shows the schematics for an application using the CC3200 preregulated 1.85-V mode.

Figure 6-2. Schematics for CC3200 Preregulated 1.85-V Mode Application

[Table](#page-57-0) 6-1 lists the bill of materials for an application using the CC3200 preregulated 1.85-V mode.

Table 6-2. Bill of Materials for CC3200 Preregulated 1.85-V Mode Application

7 Device and Documentation Support

7.1 Device Support

7.1.1 Development Support

The CC3200 evaluation board includes a set of tools and documentation to help the user during the development phase.

7.1.1.1 PinMux Tool

The CC3200 device uses pin multiplexing extensively to accommodate the large number of peripheral functions in the smallest possible package. The PinMux tool is a utility used to select the appropriate pin multiplexing configuration that meets the end application requirements. The PinMux tool makes it easy to understand the various pin multiplexing options and enables the best configuration to be chosen without error.

7.1.1.2 Radio Tool

The SimpleLink radio tool is a utility for operating and testing the CC3200 chipset designs during development of the application board. The CC3200 device has an auto-calibrated radio that enables easy connection to the antenna without requiring expertise in radio circuit design.

7.1.1.3 Uniflash Flash Programmer

The Uniflash flash programmer utility allows end users to communicate with the SimpleLink device to update the serial flash. The easy GUI interface enables flashing of files (including read-back verification option), storage format (secured and nonsecured formatting), version reading for boot loader and chip ID, and so on.

7.1.2 Device Nomenclature

To designate the stages in the product development cycle, TI assigns prefixes to the part numbers of the CC3200 device and support tools (see [Figure](#page-60-0) 7-1).

Figure 7-1. CC3200 Device Nomenclature

7.2 Documentation Support

The following documents provide support for the CC3200 device.

7.3 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms](http://www.ti.com/corp/docs/legal/termsofuse.shtml) of Use.

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7.5 Electrostatic Discharge Caution

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

7.6 Glossary

[SLYZ022](http://www.ti.com/lit/pdf/SLYZ022) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

8 Mechanical Packaging and Orderable Information

The following pages include mechanical packaging and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

MECHANICAL DATA

NOTES: All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5-1994. A.

- Β. This drawing is subject to change without notice.
- Quad Flatpack, No-leads (QFN) package configuration. \mathbb{C} .
- D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
- E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.

NOTE: A. All linear dimensions are in millimeters

PACKAGING INFORMATION

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check<http://www.ti.com/productcontent>for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

⁽⁶⁾ Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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PACKAGE MATERIALS INFORMATION

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TAPE AND REEL INFORMATION

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

TEXAS
INSTRUMENTS

PACKAGE MATERIALS INFORMATION

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*All dimensions are nominal

MECHANICAL DATA

NOTES: All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5-1994. A.

- Β. This drawing is subject to change without notice.
- Quad Flatpack, No-leads (QFN) package configuration. \mathbb{C} .
- D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
- E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.

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